

# SAM: Pushing the Limits of Saliency Prediction Models

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## Overview

- Visual saliency prediction** aims to predict where humans gazes will focus on a given image.
- Groundtruth data is collected by means of eye-tracking glasses or mouse clicks to get **eye fixation points**, which are then smoothed together to obtain the saliency map.



## Saliency Attentive Model (SAM)

### Attentive ConvLSTM

- Extension of the traditional LSTM to work on spatial features by substituting dot products with convolutional operations.
- Exploitation of the sequential nature of the LSTM to process features in an iterative way, without the concept of time.

The input of the LSTM layer  $\tilde{X}_t$  is computed through an **attentive mechanism** which produces an attention map from the previous hidden state  $H_{t-1}$  of the LSTM and the input  $X$

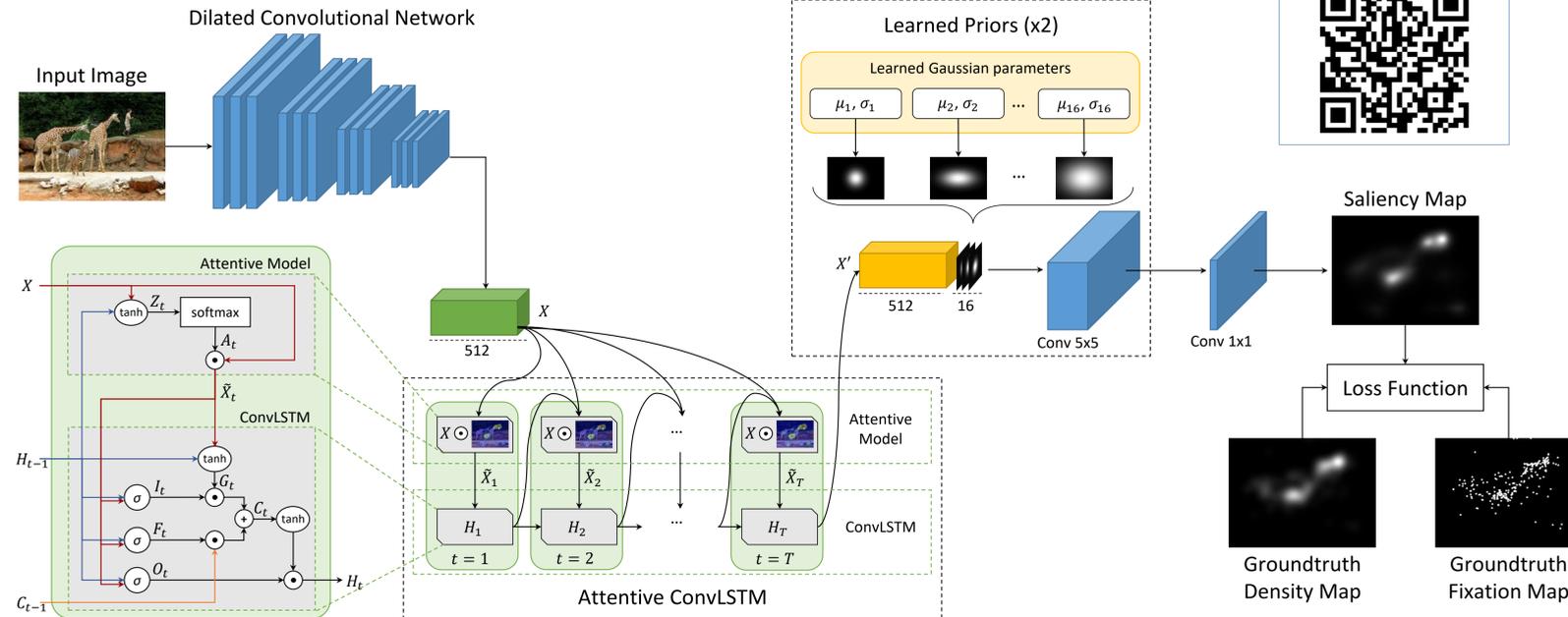
$$Z_t = V_a * \tanh(W_a * X + U_a * H_{t-1} + b_a)$$

The output of this operation is a 2-d map from which we compute a normalized spatial attention map  $A_t$  through the *softmax* operator.

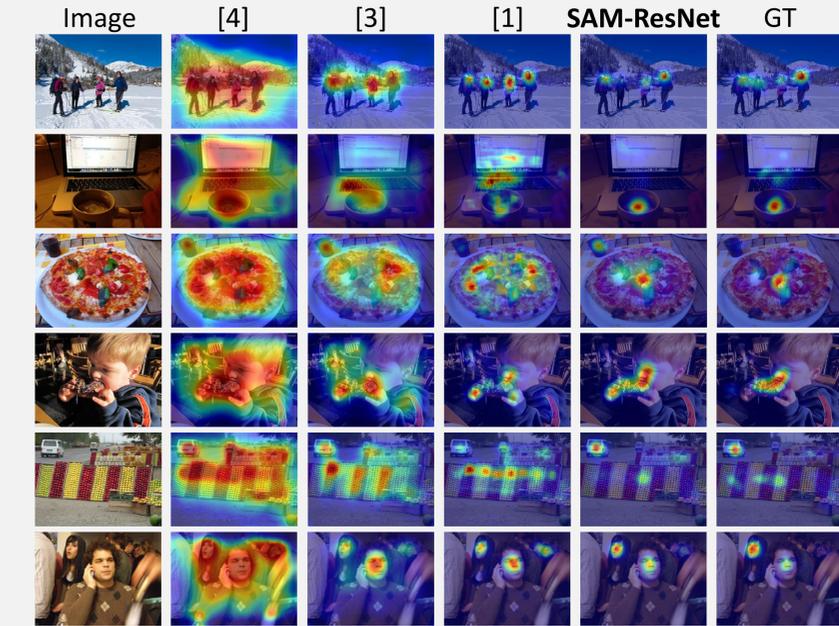
The attention map is applied to the input with an element-wise product between each channel of the feature maps and the attention map

$$\tilde{X}_t = A_t \odot X$$

### Progressive refinement of saliency maps



## Qualitative Results



### Learned Priors

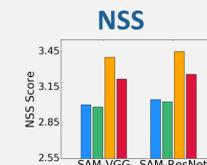
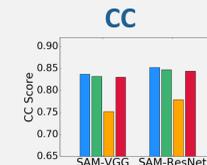
- Our network is able to learn the **center bias** present in eye fixations, without integrating this information manually.
- The model learns means and variances of a set of Gaussian functions with diagonal covariance matrix and produces a prior map for each function.

### Loss Function

To take different quality aspects into account, we define a new loss function given by a linear combination of three saliency evaluation metrics: the **NSS**, the **CC** and the **KL-Div**.

**Loss functions**

- KL-Div
- CC
- NSS
- Ours



### Dilated Convolutional Network

- We build two different versions of our model based on **VGG-16** and **ResNet-50**.
- To limit rescaling, we use dilated convolutions thus obtaining saliency maps rescaled by a factor of 8 instead of 32.

## Experimental Results

### Results on SALICON 2015

	CC	AUC	NSS
<b>SAM-Resnet</b>	<b>0.84</b>	<b>0.88</b>	<b>3.20</b>
<b>SAM-VGG</b>	0.83	0.88	3.14
ML-Net [1]	0.74	0.87	2.79
SalGAN [2]	0.78	0.78	2.46
SalNet [3]	0.62	0.86	1.86
DeepGazeII [4]	0.51	<b>0.89</b>	1.34

### Results on SALICON 2017

	CC	AUC	NSS
<b>SAM-ResNet</b>	<b>0.90</b>	<b>0.87</b>	<b>1.99</b>
<b>SAM-VGG</b>	0.89	0.86	1.97
EAD [5]	0.87	0.85	1.89
SalGAN [2]	0.84	0.86	1.82
SalNet [3]	0.76	0.84	1.56
SALICON [6]	0.66	0.81	1.56

### References:

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### Results on MIT1003, DUT-OMRON, TORONTO and PASCAL-S

	MIT1003			DUT-OMRON			TORONTO			PASCAL-S		
	CC	AUC	NSS									
GBVS [7]	0.42	0.83	1.38	0.53	0.87	1.71	0.57	0.83	1.52	0.45	0.84	1.36
Mr-CNN [8]	0.38	0.80	1.36	-	-	-	0.49	0.80	1.41	-	-	-
DVA [9]	0.64	0.87	2.38	0.67	0.91	3.09	0.72	<b>0.86</b>	2.12	0.66	0.89	2.26
<b>SAM-VGG<sub>2015</sub></b>	0.61	0.88	2.25	0.65	0.91	2.91	0.69	<b>0.86</b>	2.14	0.72	<b>0.90</b>	<b>2.48</b>
<b>SAM-VGG<sub>2017</sub></b>	0.65	<b>0.89</b>	2.33	0.69	0.91	2.95	<b>0.74</b>	<b>0.86</b>	<b>2.15</b>	0.73	0.89	2.31
<b>SAM-ResNet<sub>2015</sub></b>	0.65	0.88	<b>2.48</b>	0.69	0.91	<b>3.21</b>	0.69	<b>0.86</b>	2.12	0.69	0.89	2.34
<b>SAM-ResNet<sub>2017</sub></b>	<b>0.66</b>	<b>0.89</b>	2.35	<b>0.70</b>	<b>0.92</b>	2.97	<b>0.74</b>	<b>0.86</b>	2.14	<b>0.74</b>	<b>0.90</b>	2.34

- First place in the LSUN Saliency Prediction Challenge (CVPR 2017)!**

- State of the art on both versions of SALICON, the largest dataset available for saliency.
- Very good results on several other datasets such as MIT300, MIT1003, CAT2000, DUT-OMRON, TORONTO and PASCAL-S.